

Lecture 1. Dipole Magnetic Field and Equations of Magnetic Field Lines

1.1. Dipole Magnetic Field

Since $\nabla \cdot \mathbf{B} = 0$ we can define

$$\mathbf{B} = \nabla \times \mathbf{A} \quad (1.1)$$

where \mathbf{A} is called the vector potential. We use the bold face font to denote vector. For static magnetic field, we have

$$\nabla \times \mathbf{B} = \mu_0 \mathbf{J} \quad (1.2)$$

Substituting Eq. (1.1) into Eq. (1.2) to eliminate \mathbf{B} , it yields

$$\nabla \times (\nabla \times \mathbf{A}) = -\nabla^2 \mathbf{A} + \nabla(\nabla \cdot \mathbf{A}) = \mu_0 \mathbf{J} \quad (1.3)$$

We choose the Coulomb gauge, $\nabla \cdot \mathbf{A} = 0$, the equation (1.3) can be rewritten as

$$\nabla^2 \mathbf{A} = -\mu_0 \mathbf{J} \quad (1.4)$$

Note that:

If we choose the Coulomb gauge: $\nabla \cdot \mathbf{A} = 0$, the scalar potential will contain no electromagnetic component.

If we choose the Lorentz gauge: $\frac{1}{c^2} \frac{\partial \phi(\mathbf{x}, t)}{\partial t} + \nabla \cdot \mathbf{A}(\mathbf{x}, t) = 0$, the scalar potential will contain an electromagnetic component.

Eq. (1.4) is similar to the Poisson equation of the electrostatic potential

$$\nabla^2 \phi = -\frac{\rho_c}{\epsilon_0} \quad (1.5)$$

General solution of Eq. (1.5) can be written as

$$\phi(\mathbf{r}) = \int \frac{\rho_c(\mathbf{r}')}{4\pi\epsilon_0 |\mathbf{r} - \mathbf{r}'|} d\mathbf{r}' \quad (1.6)$$

Special Case:

The scalar potential create by a point charge q is

$$\phi = \frac{q}{4\pi\epsilon_0 r}$$

Likewise, the general solution of Eq. (1.4) can be written as

$$\mathbf{A}(\mathbf{r}) = \int \frac{\mu_0 \mathbf{J}(\mathbf{r}')}{4\pi |\mathbf{r} - \mathbf{r}'|} d\mathbf{r}' \quad (1.7)$$

Exercise 1.1.

Let $f(x) = (1+x)^\alpha$. For $0 < |x| < 1$, please determine the approximate polynomial expression of $f(x)$. That is, $f(x) \approx a_0 + a_1x + a_2x^2 + a_3x^3$

where a term with magnitude of the order of $O(x^4)$ has been ignored.

- Write down the general form of a_0, a_1, a_2, a_3 for a given α
- For $\alpha = 1/2$, write down the approximate polynomial expression of $f(x)$.
- For $\alpha = -1/2$, write down the approximate polynomial expression of $f(x)$.
- For $\alpha = -1$, write down the approximate polynomial expression of $f(x)$.
- For $\alpha = -2$, write down the approximate polynomial expression of $f(x)$.

Answers of Exercise 1.1

$$(a) \quad a_0 = 1 \quad a_1 = \alpha \quad a_2 = \alpha(\alpha - 1)/2! \quad a_3 = \alpha(\alpha - 1)(\alpha - 2)/3!$$

$$(b) \quad f(x) = \sqrt{1+x} \approx 1 + \frac{1}{2}x + \frac{-1}{8}x^2 + \frac{1}{16}x^3$$

$$(c) \quad f(x) = \frac{1}{\sqrt{1+x}} \approx 1 - \frac{1}{2}x + \frac{3}{8}x^2 - \frac{5}{16}x^3$$

$$(d) \quad f(x) = \frac{1}{1+x} \approx 1 - x + x^2 - x^3$$

$$(e) \quad f(x) = \frac{1}{(1+x)^2} \approx 1 - 2x + 3x^2 - 4x^3$$

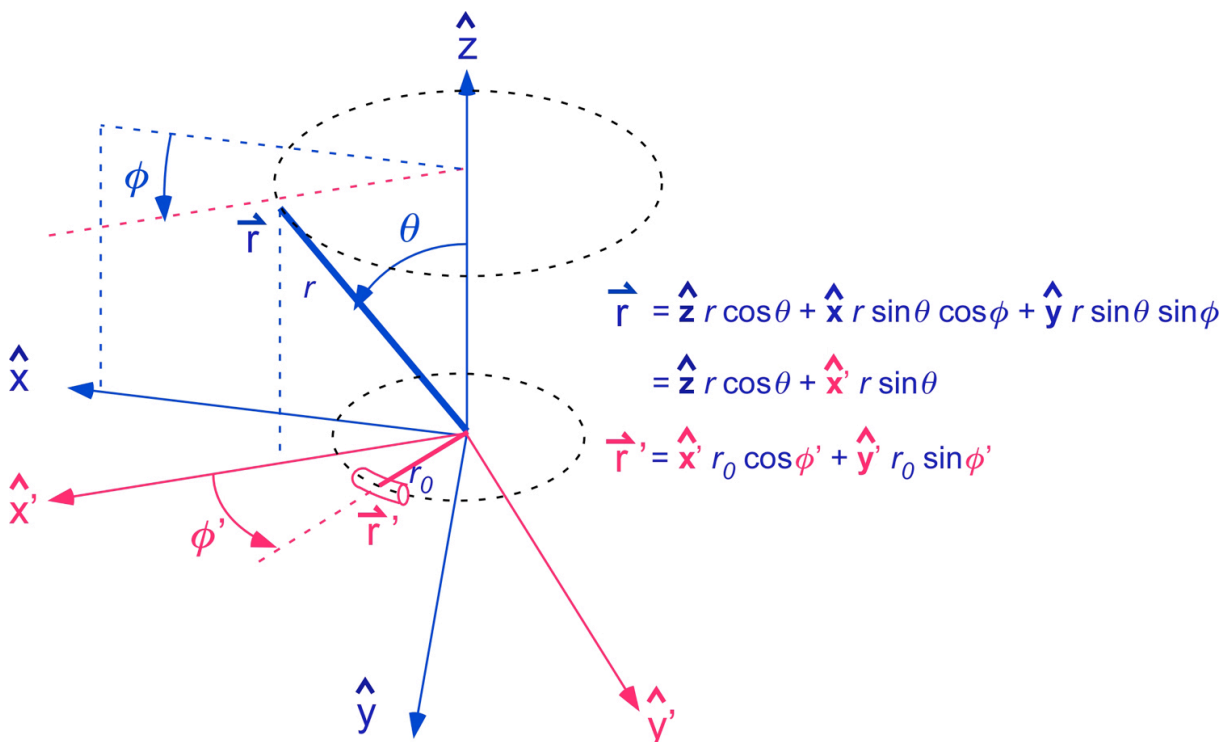


Figure 1.1. A coordinate system for the study of the field generate by a ring current

$$\mathbf{J}(\mathbf{r}') = \hat{\phi}' J_0 \delta(r' - r_0) \delta(\theta' - \frac{\pi}{2}) = (-\sin \phi' \hat{x}' + \cos \phi' \hat{y}') J_0 \delta(r' - r_0) \delta(\theta' - \frac{\pi}{2})$$

Let us consider a coordinate system as illustrated in Figure 1.1, where

$$\mathbf{r} = r \cos \theta \hat{z} + r \sin \theta \cos \phi \hat{x} + r \sin \theta \sin \phi \hat{y} = r \cos \theta \hat{z} + r \sin \theta \hat{x}'$$

$$\mathbf{r}' = r_0 \cos \phi' \hat{x}' + r_0 \sin \phi' \hat{y}'$$

$$\hat{\phi}' = -\sin \phi' \hat{x}' + \cos \phi' \hat{y}'$$

$$\hat{\phi} = \hat{y}'$$

$$\text{Given a ring current } \mathbf{J}(\mathbf{r}') = \hat{\phi}' J_0 \delta(r' - r_0) \delta(\theta' - \frac{\pi}{2}) = (-\sin \phi' \hat{x}' + \cos \phi' \hat{y}') J_0 \delta(r' - r_0) \delta(\theta' - \frac{\pi}{2})$$

The General solution of the vector potential \mathbf{A} is (Jackson, section 5.5)

$$\begin{aligned} \mathbf{A}(\mathbf{x}) &= A_\phi \hat{\phi} = A_\phi \hat{y}' \\ &= \int \frac{\mu_0 \mathbf{J}(\mathbf{r}')}{4\pi |\mathbf{r} - \mathbf{r}'|} d\mathbf{r}' \\ &= \int_{r_0 - \Delta r/2}^{r_0 + \Delta r/2} dr' \int_{(\pi/2) - \Delta\theta/2}^{(\pi/2) + \Delta\theta/2} r' d\theta' \int_0^{2\pi} r' \sin \theta' d\phi' \frac{\mu_0 J_0 \delta(r' - r_0) \delta[\theta' - (\pi/2)] \hat{\phi}'}{4\pi \sqrt{r^2 \cos^2 \theta + (r \sin \theta - r_0 \cos \phi')^2 + (r_0 \sin \phi')^2}} \\ &= \frac{\mu_0 J_0 (\Delta r)(r_0 \Delta \theta) r_0}{4\pi} \int_0^{2\pi} \frac{-\sin \phi' \hat{x}' + \cos \phi' \hat{y}'}{\sqrt{r^2 + r_0^2 - 2rr_0 \sin \theta \cos \phi'}} d\phi' \end{aligned} \quad (1.8)$$

Let $I_0 = J_0 (\Delta r)(r_0 \Delta \theta)$, $\alpha = r^2 + r_0^2$, $\beta = 2rr_0 \sin \theta$, Eq. (1.8) can be written as

$$\begin{aligned} A_\phi \hat{y}' &= \frac{\mu_0 I_0 r_0}{4\pi} (\hat{x}' \int_0^{2\pi} \frac{-\sin \phi'}{\sqrt{\alpha - \beta \cos \phi'}} d\phi' + \hat{y}' \int_0^{2\pi} \frac{\cos \phi'}{\sqrt{\alpha - \beta \cos \phi'}} d\phi') \\ &= \frac{\mu_0 I_0 r_0}{4\pi} \hat{x}' \left[\int_{\phi'=0}^{\phi'=\pi} \frac{d \cos \phi'}{\sqrt{\alpha - \beta \cos \phi'}} + \int_{\phi'=\pi}^{\phi'=2\pi} \frac{d \cos \phi'}{\sqrt{\alpha - \beta \cos \phi'}} \right] \\ &\quad + \frac{\mu_0 I_0 r_0}{4\pi} \hat{y}' \int_0^{2\pi} \frac{\cos \phi'}{\sqrt{\alpha}} \left[1 - \frac{1}{2} \left(-\frac{\beta}{\alpha} \cos \phi' \right) + O\left(\frac{\beta^2}{\alpha^2} \cos^2 \phi' \right) \right] d\phi' \\ &= \frac{\mu_0 I_0 r_0}{4\pi} \hat{x}' \left[\int_1^0 \frac{dx}{\sqrt{\alpha - \beta x}} + \int_0^1 \frac{dx}{\sqrt{\alpha - \beta x}} \right] \\ &\quad + \frac{\mu_0 I_0 r_0}{4\pi} \hat{y}' \int_0^{2\pi} \frac{\cos \phi'}{\sqrt{\alpha}} \left[1 + \frac{1}{2} \frac{\beta}{\alpha} \cos \phi' + O\left(\frac{\beta^2}{\alpha^2} \cos^2 \phi' \right) \right] d\phi' \\ &= \frac{\mu_0 I_0 r_0}{4\pi} \hat{y}' \int_0^{2\pi} \frac{\cos \phi'}{\sqrt{\alpha}} \left[1 + \frac{1}{2} \frac{\beta}{\alpha} \cos \phi' + O\left(\frac{\beta^2}{\alpha^2} \cos^2 \phi' \right) \right] d\phi' \end{aligned} \quad (1.9)$$

For $r \gg r_0$, i.e., $\alpha \gg \beta$, we can ignore the small second-order term $O\left(\frac{\beta^2}{\alpha^2} \cos^2 \phi'\right)$ in Eq.

(1.9). It yields

$$\begin{aligned}
A_\phi \hat{y}' &\approx \frac{\mu_0 I_0 r_0}{4\pi} \hat{y}' \int_0^{2\pi} \frac{\cos \phi'}{\sqrt{\alpha}} \left[1 + \frac{1}{2} \frac{\beta}{\alpha} \cos \phi' \right] d\phi' \\
&= \hat{y}' \frac{\mu_0 I_0 r_0}{4\pi} \left[\int_0^{2\pi} \cos \phi' d\phi' + \frac{\beta}{2\alpha^{3/2}} \int_0^{2\pi} \cos^2 \phi' d\phi' \right] \\
&= \hat{y}' \frac{\mu_0 I_0 r_0}{4\pi} \left[0 + \frac{\beta}{2\alpha^{3/2}} \pi \right] \\
&\approx \hat{y}' \frac{\mu_0 I_0 r_0}{4\pi} \left[\frac{2rr_0 \sin \theta}{2r^3} \pi \right] \\
&= \hat{y}' \frac{\mu_0 (I_0 \pi r_0^2) \sin \theta}{4\pi r^2}
\end{aligned} \tag{1.10}$$

Using the definition of magnetic moment $M = I_0 \pi r_0^2$, Eq. (1.10) can be written as

$$A_\phi = \frac{\mu_0 M \sin \theta}{4\pi r^2} \tag{1.11}$$

Exercise 1.2.

Please determine the dipole magnetic field \mathbf{B} from the vector potential given in Eq. (1.11)

Solution of Exercise 1.2:

Since $\mathbf{B} = \nabla \times \mathbf{A}$, it yields

$$\begin{aligned}
\mathbf{B} = \nabla \times \mathbf{A} &= \frac{1}{r^2 \sin \theta} \begin{vmatrix} \hat{r} & r\hat{\theta} & r \sin \theta \hat{\phi} \\ \frac{\partial}{\partial r} & \frac{\partial}{\partial \theta} & \frac{\partial}{\partial \phi} \\ A_r & rA_\theta & r \sin \theta A_\phi \end{vmatrix} = \frac{1}{r^2 \sin \theta} \begin{vmatrix} \hat{r} & r\hat{\theta} & r \sin \theta \hat{\phi} \\ \frac{\partial}{\partial r} & \frac{\partial}{\partial \theta} & \frac{\partial}{\partial \phi} \\ 0 & 0 & r \sin \theta \frac{\mu_0 M \sin \theta}{4\pi r^2} \end{vmatrix} \\
&= \frac{\mu_0 M}{4\pi} \frac{1}{r^2 \sin \theta} \begin{vmatrix} \hat{r} & r\hat{\theta} & r \sin \theta \hat{\phi} \\ \frac{\partial}{\partial r} & \frac{\partial}{\partial \theta} & \frac{\partial}{\partial \phi} \\ 0 & 0 & \frac{\sin^2 \theta}{r} \end{vmatrix} \\
&= \frac{\mu_0 M}{4\pi} \frac{1}{r^2 \sin \theta} \left[\hat{r} \frac{\partial}{\partial \theta} \left(\frac{\sin^2 \theta}{r} \right) - r\hat{\theta} \frac{\partial}{\partial r} \left(\frac{\sin^2 \theta}{r} \right) \right] \\
&= \frac{\mu_0 M}{4\pi} \frac{1}{r^2 \sin \theta} \left[\hat{r} \left(\frac{2 \sin \theta \cos \theta}{r} \right) + r\hat{\theta} \left(\frac{\sin^2 \theta}{r^2} \right) \right] \\
&= \frac{\mu_0 M}{4\pi} \frac{1}{r^3} \left[\hat{r} (2 \cos \theta) + \hat{\theta} (\sin \theta) \right]
\end{aligned} \tag{1.12}$$

For Earth dipole magnetic field

$$\mathbf{B} = \frac{\mu_0(-M_E)}{4\pi} \frac{1}{r^3} [\hat{r}(2\cos\theta) + \hat{\theta}(\sin\theta)] \quad (1.13)$$

It can be rewritten as

$$\mathbf{B} = \frac{-B_0}{(r/R_E)^3} [\hat{r}(2\cos\theta) + \hat{\theta}(\sin\theta)] \quad (1.14)$$

where $B_0 = |\mathbf{B}(r = R_E, \theta = \pi/2)| \approx 0.35G = 35000\gamma = 35000nT$ is the magnitude of magnetic field on the Earth' surface at the magnetic equator. The θ is called the co-latitude. The

latitude is $\lambda = \left| \frac{\pi}{2} - \theta \right|$.

1.2. Differential Equations of the Magnetic Field Line

Let us consider a segment ds along the magnetic field line, where

$$ds = \hat{r}dr + \hat{\theta}rd\theta + \hat{\phi}r\sin\theta d\phi = \hat{x}dx + \hat{y}dy + \hat{z}dz$$

It yields

$$ds = |ds| = \sqrt{dr^2 + r^2d\theta^2 + r^2\sin^2\theta d\phi^2} = \sqrt{dx^2 + dy^2 + dz^2}$$

$$\text{Let } \mathbf{B} = \hat{r}B_r + \hat{\theta}B_\theta + \hat{\phi}B_\phi = \hat{x}B_x + \hat{y}B_y + \hat{z}B_z$$

Since $\mathbf{B} \parallel ds$, it yields

$$\frac{dr}{B_r} = \frac{rd\theta}{B_\theta} = \frac{r\sin\theta d\phi}{B_\phi} = \frac{ds}{B} \quad (1.15)$$

Eq. (1.15) can be rewritten in the following system ordinary differential equations

$\frac{dr}{ds} = \frac{B_r}{B}$ $\frac{rd\theta}{ds} = \frac{B_\theta}{B}$ $\frac{r\sin\theta d\phi}{ds} = \frac{B_\phi}{B}$	(1.16)
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Likewise, $\mathbf{B} \parallel ds$ yields

$$\frac{dx}{B_x} = \frac{dy}{B_y} = \frac{dz}{B_z} = \frac{ds}{B} \quad (1.17)$$

Eq. (1.17) can be rewritten in the following system ordinary differential equations

$$\begin{aligned} \frac{dx}{ds} &= \frac{B_x}{B} \\ \frac{dy}{ds} &= \frac{B_y}{B} \\ \frac{dz}{ds} &= \frac{B_z}{B} \end{aligned} \quad (1.18)$$

Eqs. (1.16) and (1.18) can be solved by the 2nd order or the fourth order Runge-Kutta method.

1.3. Dipole Magnetic Field Line

The Earth dipole magnetic field is given in Eq. (1.14). From Eq. (1.15), the dipole magnetic field line should satisfy the following differential equation

$$\frac{dr}{2 \cos \theta} = \frac{r d\theta}{\sin \theta} \quad (1.19)$$

Solving Eq. (1.19), it yields

$$\frac{dr}{r} = \frac{2 \cos \theta d\theta}{\sin \theta} = 2 \frac{d \sin \theta}{\sin \theta}$$

Integrating along the field line, it yields

$$\int_{r(\theta=\pi/2)}^{r(\theta)} d \ln r(\theta) = 2 \int_{\sin(\theta=\pi/2)}^{\sin \theta} d \ln \sin \theta \quad (1.20)$$

Let $r(\theta = \pi / 2) = r_{eq} = LR_E$, Eq. (1.20) yields

$$r(\theta) = r_{eq} \sin^2 \theta = LR_E \sin^2 \theta \quad (1.21)$$

Exercise 1.3.

A dipole magnetic field line with a given L value will intersect with the Earth's surface at latitude λ_L . For $L = 1, 2, 3, 4, 5,$ and 6 , find the corresponding latitude λ_L .

Exercise 1.4.

Plot the dipole magnetic field line with $L = 1, 2, 3, 4, 5,$ and 6 .

Exercise 1.5.

Plot the dipole magnetic field lines, which intersect with the Earth's surface at $\lambda_L = 80^\circ, 70^\circ, 60^\circ, 50^\circ, 40^\circ, 30^\circ, 20^\circ,$ and 10° . Estimate the corresponding L values.