



Linear Algebra

Lecture 1 (Chap. 2)

Introduction to Linear Algebra and Matrix Operations

Ling-Hsiao Lyu

Institute of Space Science, National Central University

Chung-Li, Taiwan, R. O. C.

Contents

1. Introduction to Linear Algebra and Matrix Operations
2. General Solution of $Ax=b$ and Vector Space (Chapter 3)
3. Projection and Projection Matrix (Chapter 4)
4. Least Squares Fit (LSF):
Approximate Solution of $Ax=b$ (Chapter 4)
5. Determinant (Chapter 5)
6. Change of Basis (Section 7.3)
7. Eigenvalues and Eigenvectors (Chapter 6)

Solving n Linear Equations With n Unknowns

– 簡單的問題：

- 雞兔同籠問題 ($n=2$)
- 三個平面的交點 ($n=3$)

– 複雜的問題：

- Computer Tomography (CT 電腦斷層掃描)
(n : the number of pixels of the 3-D image)
- Least Square Fit (最小平方差求回歸曲線)
- Numerical Methods (particularly, the finite difference method 差分法)

殺雞用牛刀？

- 用簡單的問題，來說明牛刀的用法。
所謂牛刀小試也！
- 了解了這些牛刀怎麼用，將來才會活用這些牛刀，用來殺複雜的問題！
- 學會如何把抽象的問題，類比為簡單的幾何問題，以幫助了解問題與解題！

Basic Concepts & Outlines

- Linear Combination: $c\mathbf{u} + d\mathbf{v}$
- Linear transformation

$$T(c\mathbf{u} + d\mathbf{v}) = cT(\mathbf{u}) + dT(\mathbf{v})$$

- Gauss elimination
- Gauss-Jordan elimination
- LU algorithm
- Elementary operators:
 - Elimination
 - Permutation
 - ...

Solving Linear Equations

Example 1

- Matrix form:
$$\begin{bmatrix} 2 & -1 \\ -1 & 2 \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} 0 \\ 3 \end{bmatrix}$$

- Row picture:
– intersection of two lines
$$\begin{aligned} 2x - y &= 0 \\ -x + 2y &= 3 \end{aligned}$$

- Column picture:
– A linear combination of two vectors
$$x \begin{bmatrix} 2 \\ -1 \end{bmatrix} + y \begin{bmatrix} -1 \\ 2 \end{bmatrix} = \begin{bmatrix} 0 \\ 3 \end{bmatrix}$$

Solving Linear Equations

Example 2

- Matrix form:
$$\begin{bmatrix} 2 & -1 & 0 \\ -1 & 2 & -1 \\ 0 & -3 & 4 \end{bmatrix} \begin{bmatrix} x \\ y \\ z \end{bmatrix} = \begin{bmatrix} 0 \\ -1 \\ 4 \end{bmatrix}$$

- Row picture:
 - intersection of 3 planes
$$\begin{aligned} 2x - y &= 0 \\ -x + 2y - z &= -1 \\ -3y + 4z &= 4 \end{aligned}$$

- Column picture:
 - A linear combination of three vectors
$$x \begin{bmatrix} 2 \\ -1 \\ 0 \end{bmatrix} + y \begin{bmatrix} -1 \\ 2 \\ -3 \end{bmatrix} + z \begin{bmatrix} 0 \\ -1 \\ 4 \end{bmatrix} = \begin{bmatrix} 0 \\ -1 \\ 4 \end{bmatrix}$$

Gaussian Elimination for the Example 1

$$A = \begin{bmatrix} 2 & -1 \\ -1 & 2 \end{bmatrix}$$

$$\mathbf{x} = \begin{bmatrix} x_1 \\ x_2 \end{bmatrix}$$

$$\mathbf{b} = \begin{bmatrix} 0 \\ 3 \end{bmatrix}$$

$$A\mathbf{x} = \mathbf{b} \Rightarrow \begin{bmatrix} 2 & -1 \\ -1 & 2 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 3 \end{bmatrix} \quad A\mathbf{x} = \mathbf{b}$$

$$\begin{bmatrix} 1 & 0 \\ 1/2 & 1 \end{bmatrix} \begin{bmatrix} 2 & -1 \\ -1 & 2 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} 1 & 0 \\ 1/2 & 1 \end{bmatrix} \begin{bmatrix} 0 \\ 3 \end{bmatrix}$$

$$L^{-1}A\mathbf{x} = L^{-1}\mathbf{b}$$

$$\begin{bmatrix} 2 & -1 \\ 0 & 3/2 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 3 \end{bmatrix}$$

$$U\mathbf{x} = \mathbf{c}$$

$$\text{Since } L^{-1}A = U$$

$$\Rightarrow x_2 = 2 \Rightarrow x_1 = 1$$

$$\Rightarrow A = LU$$

2/20上課時，誤指 $L^{-1}\mathbf{b}$ 為 $U\mathbf{b}$ 。感謝黃冠瀚課後的指正！

Gaussian Elimination for the Example 2

Your Home Work:

$$A\mathbf{x} = \mathbf{b} \Rightarrow \begin{bmatrix} 2 & -1 & 0 \\ -1 & 2 & -1 \\ 0 & -3 & 4 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} 0 \\ -1 \\ 4 \end{bmatrix}$$

- Show that $A=LU$, determine L and U
- Determine \mathbf{x} from $U\mathbf{x}=\mathbf{c}$, where $\mathbf{c}=L^{-1}\mathbf{b}$

The A=LU algorithm

- Gaussian elimination:

$$A\mathbf{x} = \mathbf{b} \Rightarrow (\varepsilon_k \cdots \varepsilon_2 \varepsilon_1)A\mathbf{x} = (\varepsilon_k \cdots \varepsilon_2 \varepsilon_1)\mathbf{b}$$

$$\Rightarrow U\mathbf{x} = (\varepsilon_k \cdots \varepsilon_2 \varepsilon_1)\mathbf{b} = L^{-1}\mathbf{b}$$

Show that $A = LU$

$$(\varepsilon_k \cdots \varepsilon_2 \varepsilon_1)A = U \Rightarrow (\varepsilon_k \cdots \varepsilon_2 \varepsilon_1)^{-1}(\varepsilon_k \cdots \varepsilon_2 \varepsilon_1)A = (\varepsilon_k \cdots \varepsilon_2 \varepsilon_1)^{-1}U$$

$$\text{Since } L^{-1} = (\varepsilon_k \cdots \varepsilon_2 \varepsilon_1) \Rightarrow L = (\varepsilon_k \cdots \varepsilon_2 \varepsilon_1)^{-1} \Rightarrow A = LU$$

如何求 Elementary operator matrix 的反矩陣？

$$D^{-1} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & a & 0 \\ 0 & 0 & 1 \end{bmatrix}^{-1} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1/a & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

$$E^{-1} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ b & 0 & 1 \end{bmatrix}^{-1} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ -b & 0 & 1 \end{bmatrix}$$

將二式乘以a倍 要還原 就乘以1/a倍

將三式加b倍的一式 要還原就減去b倍的一式

What is Algorithm?

- algorithm
 - a process or set of rules or steps to be followed in calculations or other problem-solving operations, esp. by a computer

Permutation

- Row exchange

$$\begin{array}{l} 2x - y = 0 \\ -x + 2y - z = -1 \\ -3y + 4z = 4 \end{array} \Rightarrow \begin{array}{c} \curvearrowright \\ \left[\begin{array}{ccc} 2 & -1 & 0 \\ -1 & 2 & -1 \\ 0 & -3 & 4 \end{array} \right] \begin{array}{c} \left[\begin{array}{c} x \\ y \\ z \end{array} \right] = \left[\begin{array}{c} 0 \\ -1 \\ 4 \end{array} \right] \end{array} \curvearrowleft \end{array}$$

$$\begin{array}{l} -x + 2y - z = -1 \\ 2x - y = 0 \\ -3y + 4z = 4 \end{array} \Rightarrow \begin{array}{c} \left[\begin{array}{ccc} -1 & 2 & -1 \\ 2 & -1 & 0 \\ 0 & -3 & 4 \end{array} \right] \begin{array}{c} \left[\begin{array}{c} x \\ y \\ z \end{array} \right] = \left[\begin{array}{c} -1 \\ 0 \\ 4 \end{array} \right] \end{array}$$

Permutation : Row exchange

$$\begin{bmatrix} 2 & -1 & 0 \\ -1 & 2 & -1 \\ 0 & -3 & 4 \end{bmatrix} \begin{bmatrix} x \\ y \\ z \end{bmatrix} = \begin{bmatrix} 0 \\ -1 \\ 4 \end{bmatrix} \quad \mathbf{Ax} = \mathbf{b}$$

$$\begin{bmatrix} 0 & 1 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 2 & -1 & 0 \\ -1 & 2 & -1 \\ 0 & -3 & 4 \end{bmatrix} \begin{bmatrix} x \\ y \\ z \end{bmatrix} = \begin{bmatrix} 0 & 1 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 0 \\ -1 \\ 4 \end{bmatrix} \quad (\mathbf{PA})\mathbf{x} = \mathbf{Pb}$$

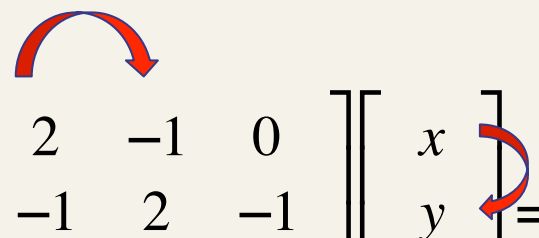
$$\begin{bmatrix} -1 & 2 & -1 \\ 2 & -1 & 0 \\ 0 & -3 & 4 \end{bmatrix} \begin{bmatrix} x \\ y \\ z \end{bmatrix} = \begin{bmatrix} -1 \\ 0 \\ 4 \end{bmatrix}$$


Permutation matrix 的反矩陣：若將一式與二式交換 要還原 就將兩者再交換一次

2/20上課時，第一式右式錯誤。感謝助教林筵捷的指正！

Permutation

- Column exchange

$$x \begin{bmatrix} 2 \\ -1 \\ 0 \end{bmatrix} + y \begin{bmatrix} -1 \\ 2 \\ -3 \end{bmatrix} + z \begin{bmatrix} 0 \\ -1 \\ 4 \end{bmatrix} = \begin{bmatrix} 0 \\ -1 \\ 4 \end{bmatrix} \Rightarrow \begin{bmatrix} 2 & -1 & 0 \\ -1 & 2 & -1 \\ 0 & -3 & 4 \end{bmatrix} \begin{bmatrix} x \\ y \\ z \end{bmatrix} = \begin{bmatrix} 0 \\ -1 \\ 4 \end{bmatrix}$$


$$y \begin{bmatrix} -1 \\ 2 \\ -3 \end{bmatrix} + x \begin{bmatrix} 2 \\ -1 \\ 0 \end{bmatrix} + z \begin{bmatrix} 0 \\ -1 \\ 4 \end{bmatrix} = \begin{bmatrix} 0 \\ -1 \\ 4 \end{bmatrix} \Rightarrow \begin{bmatrix} -1 & 2 & 0 \\ 2 & -1 & -1 \\ -3 & 0 & 4 \end{bmatrix} \begin{bmatrix} y \\ x \\ z \end{bmatrix} = \begin{bmatrix} 0 \\ -1 \\ 4 \end{bmatrix}$$


3/3上課時，-3誤植為3。感謝同學的指正！

Permutation: column exchange

$$\begin{bmatrix} 2 & -1 & 0 \\ -1 & 2 & -1 \\ 0 & -3 & 4 \end{bmatrix} \begin{bmatrix} x \\ y \\ z \end{bmatrix} = \begin{bmatrix} 0 \\ -1 \\ 4 \end{bmatrix} \quad \mathbf{Ax} = \mathbf{b}$$

$$\begin{bmatrix} 2 & -1 & 0 \\ -1 & 2 & -1 \\ 0 & -3 & 4 \end{bmatrix} \begin{bmatrix} 0 & 1 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 0 & 1 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} x \\ y \\ z \end{bmatrix} = \begin{bmatrix} 0 \\ -1 \\ 4 \end{bmatrix}$$

Permutation matrix 的反矩陣：
將一式與二式交換 要還原 將兩者再交換一次

$$(\mathbf{AP})(\mathbf{P}^{-1}\mathbf{x}) = \mathbf{b}$$

$$\begin{bmatrix} -1 & 2 & 0 \\ 2 & -1 & -1 \\ -3 & 0 & 4 \end{bmatrix} \begin{bmatrix} y \\ x \\ z \end{bmatrix} = \begin{bmatrix} 0 \\ -1 \\ 4 \end{bmatrix}$$

The **Algorithm** for Solving Linear Equations

- Gaussian Elimination:
 - reduce to an **echelon** form
- Gauss-Jordan Elimination: (**augmented** matrix)
- The elementary matrices:
 - The elimination matrices
 - The permutation matrices
- The $A=LU$ or $A=LDU$ algorithm:

What is an echelon form ?

- echelon form
$$\begin{bmatrix} a & b & d & f & i & m & r \\ 0 & c & e & g & j & n & s \\ 0 & 0 & 0 & h & k & o & t \\ 0 & 0 & 0 & 0 & l & p & u \\ 0 & 0 & 0 & 0 & 0 & q & v \end{bmatrix}$$

What is an augmented matrix?

- augmented matrix

$$\left[\begin{array}{ccc|ccc} a & b & c & 1 & 0 & 0 \\ d & e & f & 0 & 1 & 0 \\ g & h & i & 0 & 0 & 1 \end{array} \right]$$

Homework #1-1

- Prove that by applying the “Gauss-Jordan Elimination” algorithm to an invertible matrix A , you can obtain A^{-1} , which is shown on the right-hand side of the final augmented matrix.

Why do we want to factorize $A=LU$?

- Because it is easy to determine the inverse and determinant of the elimination matrix and the permutation matrix
- $A\mathbf{x}=\mathbf{b} \rightarrow L^{-1}L\mathbf{U}\mathbf{x}=L^{-1}\mathbf{b} \rightarrow \mathbf{U}\mathbf{x}=\mathbf{c}$
 - Where $\mathbf{U}\mathbf{x}=\mathbf{c}$ is very easy to solve (Chap. 2 & Chap. 3)
- $A=LU$ then
 - $\det(A)=\det(L)\det(U)=\det(U)=$ 對角線的連乘積 (Chap. 5)
- $A_1=L_1R_1 \rightarrow A_2=R_1L_1=L_2R_2 \rightarrow \dots$ a matrix with decreasing eigen values on its diagonal ! (Chap. 6)

Lecture 1
Part B
Transpose, Inverse, &
special matrices

Transpose and Inverse

- Definitions

- A^T (transpose of matrix A) : $A_{ij} = (A^T)_{ji}$

- A^{-1} (inverse matrix of a **square** matrix A) :
 $AA^{-1}=A^{-1}A=1$

- **口訣**：先穿襪子，再穿鞋子。回復時～
先脫鞋子，再脫襪子。

$$(AB)^T = B^T A^T \quad (AB)^{-1} = B^{-1} A^{-1}$$

$$(AB)^{-1} = B^{-1}A^{-1}$$

• 證明：

$$(AB)^{-1}(AB) = \mathbf{1}$$

(1)

$$B^{-1}A^{-1}(AB) = B^{-1}(A^{-1}A)B = B^{-1}(\mathbf{1})B = B^{-1}B = \mathbf{1}$$

(2)

Equations (1) and (2) yield

$$(AB)^{-1} = B^{-1}A^{-1}$$

$$(AB)^{-1} = B^{-1}A^{-1}$$

- Example:

$$\text{Let } A = \begin{bmatrix} 1 & 0 & 0 \\ -1 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \quad B = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & -1 & 1 \end{bmatrix}$$

Determine A^{-1} , B^{-1} , $C=AB$, and $D=B^{-1}A^{-1}$

Verify your results by checking if they satisfy the following relations

$$AA^{-1} = \mathbf{1} \quad , \quad BB^{-1} = \mathbf{1} \quad , \quad \text{and} \quad CD = \mathbf{1}$$

$$(AB)^T = B^T A^T$$

有兩種看法去驗證這個關係式。

第一種看法：

Let us consider two matrices $A_{m \times n}$ and $B_{n \times l}$

We have

$$A_{m \times n} B_{n \times l} = C_{m \times l}, \quad (A^T)_{n \times m}, \quad (B^T)_{l \times n}, \quad (C^T)_{l \times m}$$

$$\text{and } (B^T)_{l \times n} (A^T)_{n \times m} = (B^T A^T)_{l \times m}$$

\Rightarrow Both $(AB)^T = (C^T)$ and $(B^T A^T)$ are $l \times m$ matrices

$$(\mathbf{AB})^T = \mathbf{B}^T \mathbf{A}^T$$

第二種看法：

Let us consider the linear equations

$$2x - 3y = -4$$

$$-x + 2y = 3$$

They can be rewritten in the following matrix forms. Thus, we conclude that $(\mathbf{AB})^T = \mathbf{B}^T \mathbf{A}^T$.

$$\begin{bmatrix} 2 & -3 \\ -1 & 2 \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} -4 \\ 3 \end{bmatrix} \quad \text{or} \quad \mathbf{Ax} = \mathbf{b}$$

$$\begin{bmatrix} x & y \end{bmatrix} \begin{bmatrix} 2 & -1 \\ -3 & 2 \end{bmatrix} = \begin{bmatrix} -4 & 3 \end{bmatrix} \quad \text{or} \quad \mathbf{x}^T \mathbf{A}^T = \mathbf{b}^T$$

$(AB)^T = B^T A^T$ (比較嚴謹的證明)

Let us consider two matrices $A_{m \times n}$ and $B_{n \times l}$

For all $i \in \{1, \dots, m\}$ and $j \in \{1, \dots, l\}$, we have

$$\left((AB)^T \right)_{ji} = (AB)_{ij}$$

$$= \sum_{k=1}^n A_{ik} B_{kj}$$

$$= \sum_{k=1}^n (A^T)_{ki} (B^T)_{jk}$$

$$= \sum_{k=1}^n (B^T)_{jk} (A^T)_{ki}$$

$$= (B^T A^T)_{ji}$$

Definition of the transpose of a matrix

Definition of matrix multiplication

Definition of the transpose of a matrix

Exchange of scalar multiplication

Definition of matrix multiplication

注意，
這裡的
足標與
上課時
所用略
有不同

因為上式對所有的 ji 分量都成立，故得證 $(AB)^T = B^T A^T$ 27

Symmetric Matrix & Anti-symmetric Matrix

- Definitions
 - M is a symmetric matrix if $M^T = M$
 - M is an anti-symmetric matrix if $M^T = -M$

Decomposing a Square Matrix M to $M^S + M^A$

If M is a **square** matrix then M can be decomposed into a symmetric matrix M^S and an anti-symmetric matrix M^A

$$M = M^S + M^A$$

where

$$M^S = (M + M^T)/2$$

$$M^A = (M - M^T)/2$$

How to build a symmetric matrix (method 2)

If R is an $m \times n$ **rectangular** matrix then

- $R^T R$ is an $n \times n$ symmetric matrix
- $R R^T$ is an $m \times m$ symmetric matrix

Proof:

$$(R^T R)^T = (R)^T (R^T)^T = R^T R \rightarrow R^T R \text{ is symmetric}$$

$$(R R^T)^T = (R^T)^T (R)^T = R R^T \rightarrow R R^T \text{ is symmetric}$$

- LDL^T is also a symmetric matrix

Symmetric Matrix

If M is a symmetric matrix, then

- M^{-1} is a symmetric matrix
- $M=LDL^T$ and $M=Q\Lambda Q^T$
 - The number of positive pivots in D and positive eigenvalues in Λ is the same.
 - A has real eigenvalues and orthonormal eigen vectors in Q 以後教

Expressions and Definitions

- Expressions of vector

- Hand writing: \vec{v} or \underline{v} or $|v\rangle$ **or** \vec{v}^T or \underline{v}^T or $\langle v|$

- Typeface: boldface for vector, i.e., \mathbf{v} **or** \mathbf{v}^T

- Matrix expression of vectors: $\begin{bmatrix} v_1 \\ v_2 \\ v_3 \end{bmatrix}$ **or** $[v_1 \ v_2 \ v_3]$
where the vector is defined by

$$\vec{v} = v_1 \hat{e}_1 + v_2 \hat{e}_2 + v_3 \hat{e}_3 = \sum v_i \hat{e}_i = v_i \hat{e}_i$$

$$\mathbf{v} = v_1 \mathbf{e}_1 + v_2 \mathbf{e}_2 + v_3 \mathbf{e}_3 = \sum_i v_i \mathbf{e}_i = v_i \mathbf{e}_i$$

Vector Products

- Definitions of vector products
 - inner product: $\mathbf{v} \cdot \mathbf{w}$
 - the multiplying of the projection of one vector to the other vector
 - cross product: $\mathbf{v} \times \mathbf{w}$
 - size and normal direction of the area determined by the two vectors
 - dyad product: \mathbf{vw}

Matrix Expression of Vector Products

- inner product:
$$\mathbf{v} \cdot \mathbf{w} = \begin{bmatrix} v_1 & v_2 & v_3 \end{bmatrix} \begin{bmatrix} w_1 \\ w_2 \\ w_3 \end{bmatrix}$$
- cross product:
$$\mathbf{v} \times \mathbf{w} = \begin{bmatrix} 0 & -v_3 & v_2 \\ v_3 & 0 & -v_1 \\ -v_2 & v_1 & 0 \end{bmatrix} \begin{bmatrix} w_1 \\ w_2 \\ w_3 \end{bmatrix}$$
- dyad product:
$$\mathbf{vw} = \begin{bmatrix} v_1 \\ v_2 \\ v_3 \end{bmatrix} \begin{bmatrix} w_1 & w_2 & w_3 \end{bmatrix} = \begin{bmatrix} v_1 w_1 & v_1 w_2 & v_1 w_3 \\ v_2 w_1 & v_2 w_2 & v_2 w_3 \\ v_3 w_1 & v_3 w_2 & v_3 w_3 \end{bmatrix}$$

Special Matrices (1)

- Definitions

- A is a symmetric matrix if $A^T = A$

- A is a anti-symmetric matrix if $A^T = -A$

- A is an orthogonal matrix if $A^T = A^{-1}$ 以後教

- Define z^* : if $z=a+ib$ then $z^*=a-ib$

- A is a Hermitian matrix if $A^H=(A^T)^*=A$ 以後教

- A is a unitary matrix if $A^H=(A^T)^*=A^{-1}$ 以後教

Special Matrices (2)

- Identity matrix: $\mathbf{1}$ 教過了！
- Elimination matrix: 教過了！
- Permutation matrix: 教過了！
- Projection matrix: $P=P^2=P^T$ 以後教
- Rotation matrix: 以後教
- Reflection matrix: $Q=\mathbf{1}-2\mathbf{u}\mathbf{u}^T$ 以後教
- Householder matrix: $Q^T=Q^{-1}=Q$ 以後教

Row Operation, Column Operation, & Matrices Multiplication

Column Operation

$$\text{Solve } \mathbf{x}^T A^T = \mathbf{b}^T \quad \text{or} \quad \begin{bmatrix} x_1 & x_2 \end{bmatrix} \begin{bmatrix} 1 & 2 \\ 3 & 2 \end{bmatrix} = \begin{bmatrix} b_1 & b_2 \end{bmatrix}$$

choose the **Column** eliminator on the **right** to be $\begin{bmatrix} 1 & -2 \\ 0 & 1 \end{bmatrix}$

$$\Rightarrow \begin{bmatrix} x_1 & x_2 \end{bmatrix} \begin{bmatrix} 1 & 2 \\ 3 & 2 \end{bmatrix} \begin{bmatrix} 1 & -2 \\ 0 & 1 \end{bmatrix} = \begin{bmatrix} b_1 & b_2 \end{bmatrix} \begin{bmatrix} 1 & -2 \\ 0 & 1 \end{bmatrix}$$

$$\Rightarrow \begin{bmatrix} x_1 & x_2 \end{bmatrix} \begin{bmatrix} 1 & 0 \\ 3 & -4 \end{bmatrix} = \begin{bmatrix} b_1 & -2b_1 + b_2 \end{bmatrix}$$

Row Operation

To solve $\mathbf{x}^T \mathbf{A}^T = \mathbf{b}^T$ or $\begin{bmatrix} x_1 & x_2 \end{bmatrix} \begin{bmatrix} 1 & 2 \\ 3 & 2 \end{bmatrix} = \begin{bmatrix} b_1 & b_2 \end{bmatrix}$

is equivalent to solve $\mathbf{A}\mathbf{x} = \mathbf{b}$ or $\begin{bmatrix} 1 & 3 \\ 2 & 2 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} b_1 \\ b_2 \end{bmatrix}$

$$\Rightarrow \begin{bmatrix} 1 & 0 \\ -2 & 1 \end{bmatrix} \begin{bmatrix} 1 & 3 \\ 2 & 2 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} 1 & 0 \\ -2 & 1 \end{bmatrix} \begin{bmatrix} b_1 \\ b_2 \end{bmatrix}$$

$$\Rightarrow \begin{bmatrix} 1 & 3 \\ 0 & -4 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} b_1 \\ -2b_1 + b_2 \end{bmatrix}$$

Matrices multiplication

可利用
$$\begin{bmatrix} a & b \\ c & d \end{bmatrix} \begin{bmatrix} w & x \\ y & z \end{bmatrix} = \begin{bmatrix} a \\ c \end{bmatrix} \begin{bmatrix} w & x \end{bmatrix} + \begin{bmatrix} b \\ d \end{bmatrix} \begin{bmatrix} y & z \end{bmatrix}$$

證明

$$\begin{bmatrix} 1 & 2 \\ 3 & 2 \end{bmatrix} \begin{bmatrix} 1 & 2 \\ 0 & 1 \end{bmatrix} = \begin{bmatrix} 2 & 1 \\ 2 & 3 \end{bmatrix} \begin{bmatrix} 0 & 1 \\ 1 & 2 \end{bmatrix}$$

$$\begin{bmatrix} 1 & 2 \\ 3 & 2 \end{bmatrix} \begin{bmatrix} 1 & 2 \\ 0 & 1 \end{bmatrix} = \begin{bmatrix} 1 & 4 \\ 3 & 8 \end{bmatrix}$$

$$= \begin{bmatrix} 1 \\ 3 \end{bmatrix} \begin{bmatrix} 1 & 2 \end{bmatrix} + \begin{bmatrix} 2 \\ 2 \end{bmatrix} \begin{bmatrix} 0 & 1 \end{bmatrix} = \begin{bmatrix} 2 \\ 2 \end{bmatrix} \begin{bmatrix} 0 & 1 \end{bmatrix} + \begin{bmatrix} 1 \\ 3 \end{bmatrix} \begin{bmatrix} 1 & 2 \end{bmatrix}$$

$$= \begin{bmatrix} 2 & 1 \\ 2 & 3 \end{bmatrix} \begin{bmatrix} 0 & 1 \\ 1 & 2 \end{bmatrix}$$

Matrices multiplication

$$\begin{bmatrix} 1 & 2 \\ 3 & 2 \end{bmatrix} \begin{bmatrix} 1 & 2 \\ 0 & 1 \end{bmatrix} = \begin{bmatrix} 1 & 4 \\ 3 & 8 \end{bmatrix} = \begin{bmatrix} 1 \\ 3 \end{bmatrix} \begin{bmatrix} 1 & 2 \end{bmatrix} + \begin{bmatrix} 2 \\ 2 \end{bmatrix} \begin{bmatrix} 0 & 1 \end{bmatrix} = \begin{bmatrix} 1 \cdot [1 & 2] \\ 3 \cdot [1 & 2] \end{bmatrix} + \begin{bmatrix} 2 \cdot [0 & 1] \\ 2 \cdot [0 & 1] \end{bmatrix}$$

$$= \begin{bmatrix} 1 \cdot [1 & 2] + 2 \cdot [0 & 1] \\ 3 \cdot [1 & 2] + 2 \cdot [0 & 1] \end{bmatrix} \quad \text{i.e.,} \quad \begin{bmatrix} 1 & 2 \\ 3 & 2 \end{bmatrix} \begin{bmatrix} 1 & 2 \\ 0 & 1 \end{bmatrix} = \begin{bmatrix} 1 & 4 \\ 3 & 8 \end{bmatrix} \quad \text{yields row operation}$$

$$\Rightarrow 1 \cdot [1 \ 2] + 2 \cdot [0 \ 1] = [1 \ 2] \begin{bmatrix} 1 & 2 \\ 0 & 1 \end{bmatrix} = [1 \ 4]$$

$$\& \ 3 \cdot [1 \ 2] + 2 \cdot [0 \ 1] = [3 \ 2] \begin{bmatrix} 1 & 2 \\ 0 & 1 \end{bmatrix} = [3 \ 8]$$

Put the **Row Operator** on the **left!** e.g.,
row elimination, or
row permutation

Matrices multiplication

$$\begin{bmatrix} 1 & 2 \\ 3 & 2 \end{bmatrix} \begin{bmatrix} 1 & 2 \\ 0 & 1 \end{bmatrix} = \begin{bmatrix} 1 & 4 \\ 3 & 8 \end{bmatrix} = \begin{bmatrix} 1 \\ 3 \end{bmatrix} \begin{bmatrix} 1 & 2 \end{bmatrix} + \begin{bmatrix} 2 \\ 2 \end{bmatrix} \begin{bmatrix} 0 & 1 \end{bmatrix}$$

$$= \begin{bmatrix} 1 \cdot \begin{bmatrix} 1 \\ 3 \end{bmatrix} & 2 \cdot \begin{bmatrix} 1 \\ 3 \end{bmatrix} \end{bmatrix} + \begin{bmatrix} 0 \cdot \begin{bmatrix} 2 \\ 2 \end{bmatrix} & 1 \cdot \begin{bmatrix} 2 \\ 2 \end{bmatrix} \end{bmatrix} = \begin{bmatrix} 1 \cdot \begin{bmatrix} 1 \\ 3 \end{bmatrix} + 0 \cdot \begin{bmatrix} 2 \\ 2 \end{bmatrix} & 2 \cdot \begin{bmatrix} 1 \\ 3 \end{bmatrix} + 1 \cdot \begin{bmatrix} 2 \\ 2 \end{bmatrix} \end{bmatrix}$$

i.e.,

$$\begin{bmatrix} 1 & 2 \\ 3 & 2 \end{bmatrix} \begin{bmatrix} 1 & 2 \\ 0 & 1 \end{bmatrix} = \begin{bmatrix} 1 & 4 \\ 3 & 8 \end{bmatrix} \Rightarrow 1 \cdot \begin{bmatrix} 1 \\ 3 \end{bmatrix} + 0 \cdot \begin{bmatrix} 2 \\ 2 \end{bmatrix} = \begin{bmatrix} 1 & 2 \\ 3 & 2 \end{bmatrix} \begin{bmatrix} 1 \\ 0 \end{bmatrix} = \begin{bmatrix} 1 \\ 3 \end{bmatrix}$$

$$\& 2 \cdot \begin{bmatrix} 1 \\ 3 \end{bmatrix} + 1 \cdot \begin{bmatrix} 2 \\ 2 \end{bmatrix} = \begin{bmatrix} 1 & 2 \\ 3 & 2 \end{bmatrix} \begin{bmatrix} 2 \\ 1 \end{bmatrix} = \begin{bmatrix} 4 \\ 8 \end{bmatrix}$$

Put the **Column Operator**
on the **right!**

e.g., column elimination,
or column permutation